

## Validation and Calibration of MSU/AMSU Measurements and Radiosonde Observations Using GPS RO Data for Improving Stratospheric and Tropospheric Temperature Trend Analysis

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## Outline

- Brief Project Overview
- Approach
- Results/Accomplishments
- Validation Strategy/Results
- Algorithm/Product Maturity
- Issues/Risks & Work-Off Plans
- Research-to-Operations or Delivery Plan
- Schedule
- Resources

## **Overview**

### Goals/Challenges:

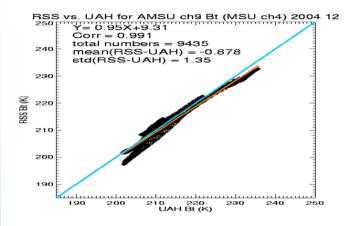
- 1. Quantify the quality of RO data, and use GPS RO data to help identify a set of operational radiosonde network
- 2. Using GPS RO data in the stratosphere and the identified radiosondes in the troposphere to validate MSU and AMSU measurements from RSS, UAH, and NESDIS
- 3.Generating long-term stratospheric and tropospheric climate quality temperature datasets by reprocessing nine years of AMSU/MSU data from 2001 to 2009

# Challenges of defining Climate Trend using MSU/AMSU data

### Satellites: Comparability and Reproducibility ?

- 1) Not designed for climate monitoring
- 2) Changing platforms and instruments (No Comparability)
- a. Satellite dependent bias, b. geo-location dependent bias, c. orbital drift dependent bias
- 3) Different processing/merging method lead to different trends (RSS vs. UAH).

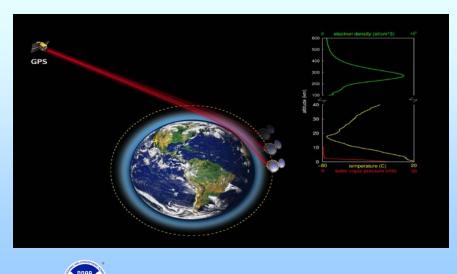
(No Reproducibility)

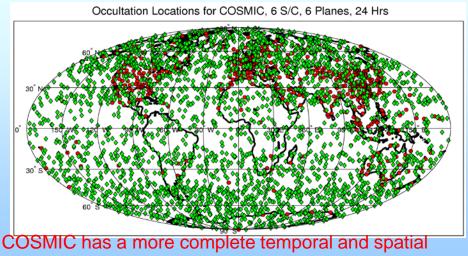




## **Overview** Characteristics of GPS RO Data

- Measure of time delay: no calibration is needed
- Requires no first guess sounding
- Uniform spatial/temporal coverage
- High precision, no geo- location dependent bias
- No satellite- to- satellite bias
- Independent of processing procedures





global coverage

## **Overview**

### Source Data –

- CHAMP data (from Jan. 2002 to Dec. 2008) from UCAR CDAAC,
- COSMIC data (from June 2006 current) from UCAR CDAAC
- MSU/AMSU data from NESDIS (NESDIS<sub>OPR</sub>) for NOAA 14 (MSU), NOAA 15 (AMSU), NOAA 16 (AMSU) and NOAA 18 (AMSU) from 2002 to 2009
- Aqua AMSU from 2002 to current, RSS, UAH and NESDIS<sub>NEW</sub> data from their related FTP sites
- Global radiosonde data from NCAR archive, and
- ECMWF data from NCAR archive.

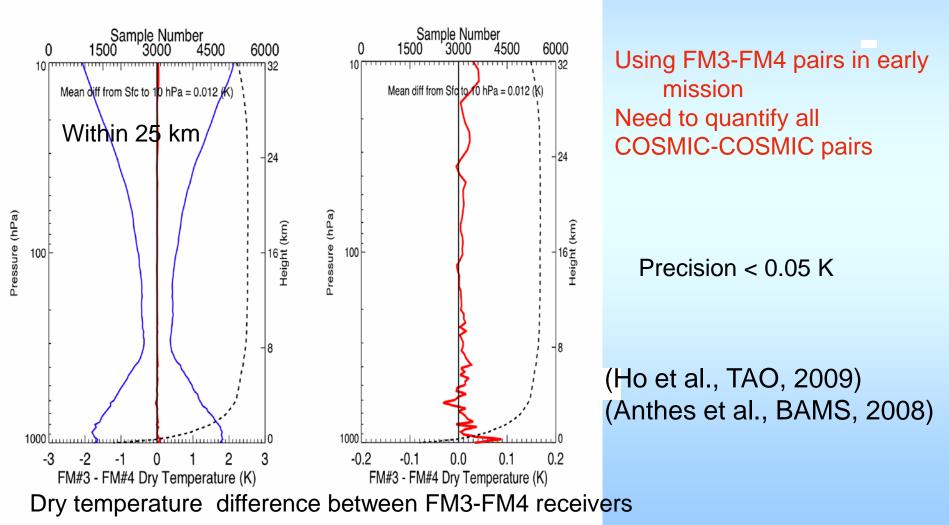
### Deliverables:

- High quality temperature records in both troposphere and stratosphere
- Traceable standards for GPS RO metadata, including the change of observing practices, the bending angle, phase, amplitude, and time delay of radio signals.
- Identified radiosonde sets.
- ECVs addressed:
- Temperature records in both troposphere and stratosphere
- Current/expected user communities:
- NOAA, NASA, NCEP, ECMWF, national/international climate/satellite community



## **Approaches**

### I. Quantify the quality of RO data

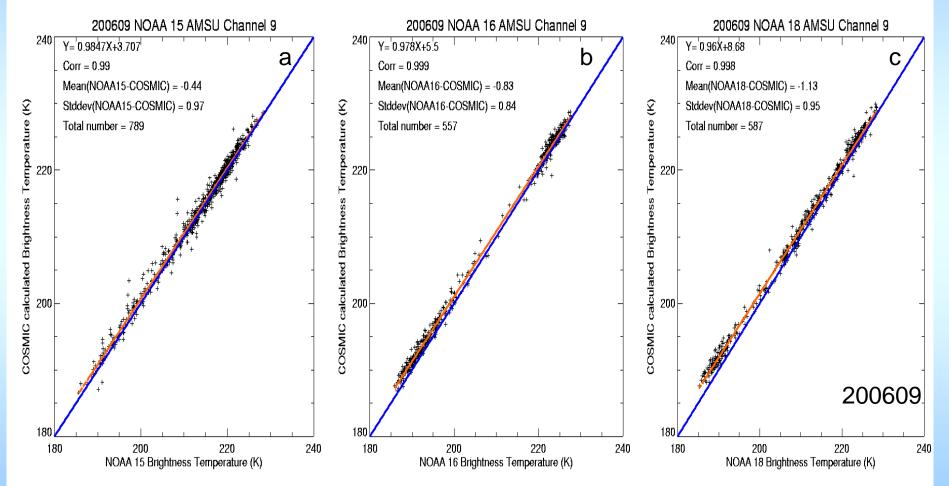


Shu-peng Ben Ho, UCAR/COSMIC

## **Approaches**

II. Use RO-simulated MSU/AMSU Tbs to calibrate/validate MSU/AMSU Tbs

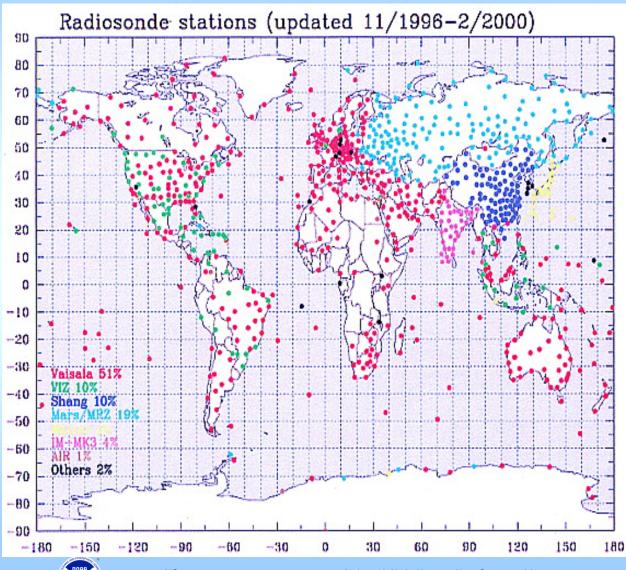
### Resolve satellite dependent bias



N15, N16 and N18 AMSU calibration against COSMIC (Ho et al, TAO/COSMIC special issue 2009)

## **Approaches**

III. Using RO data to assess the quality of radiosonde data



8

| Region | Sonde<br>Type | Matched<br>Sample |  |  |
|--------|---------------|-------------------|--|--|
| Russia | AVK-<br>MRZ   | 2000<br>(20%)     |  |  |
| China  | Shang         | 650<br>(6.1%)     |  |  |
| USA    | VIZ-B2        | 600<br>(5.9%)     |  |  |
| Others | Vaisala       | 3140<br>(30%)     |  |  |

I. Quantify the Precision/Accuracy/Stability of RO data

### Global COSMIC, CHAMP, SAC-C, GRACE-A, Metop/GRAS Comparison

#### Within 60 Mins, and 50 Km Sample Number 2000 3000 Sample Number 400 600 1000 4000 1000 5000 0 200 800 Mean Bias = -0.089 Mean Bias = -0.094 Abs(Mean) Bias = 0.094 Abs(Mean) Bias = 0.089 MeanSD = 1.452MeanSD + 1.342 30 30 Height (Km) Height (Km) 20 20 10 10 4 -6 -4 0 6 -4 -2 4 T grace - T cosmic (K) T champ - T cosmic (K)

- Comparison of measurements between old and new instrument
- CHAMP launched in 2001
- COSMIC launched 2006
- GRACE launched 2002

# Don't need to have stable calibration reference

CHAMP-COSMIC 2007-2008

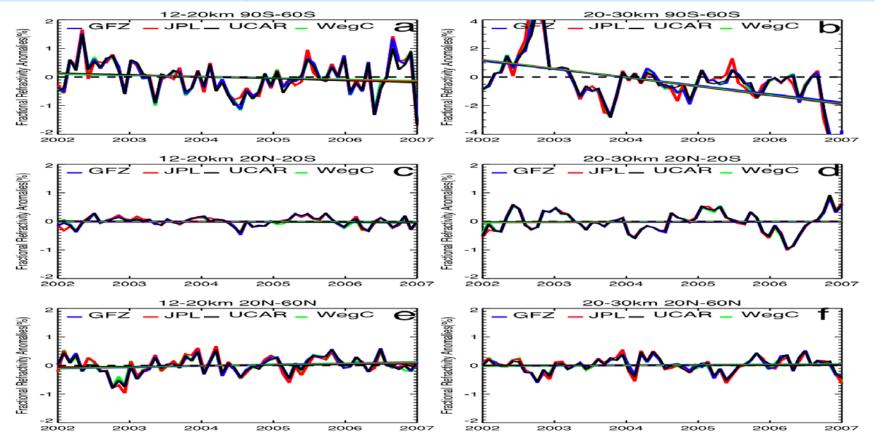
GRACE-COSMIC 2006



II. Quantify the Reproducibility of RO data, the uncertainty of RO data

### Comparisons RO data processed by GFZ, JPL, UCAR, and WegC

**Fractional Refractivity Anomalies** 



(Ho et al. JGR, 2009) Shu-peng Ben Ho, UCAR/COSMIC http://www.cosmic.ucar.edu/~spho/

III. Use of RO Data to Identify the Location/local-time Dependent Brightness Temperature Biases for regional Climate Studies

#### To resolve geo-location dependent bias 200707 180 2 AMSU-COSMIC Tb (K) 170 Mean Solar Zenith Angle (degree) 160 Zero AMSU-COSMIC Tb line (K) 150 1 140 130 12 AMSU-COSMIC Tb (K) 110 Ο 100 Mean Solar Zenith 90 80 - 1 70 60 50 40 -2 30 20 10 -3 -50 O 50 Latitude (degree)

Unbiased, good anchor for radiance assimilation

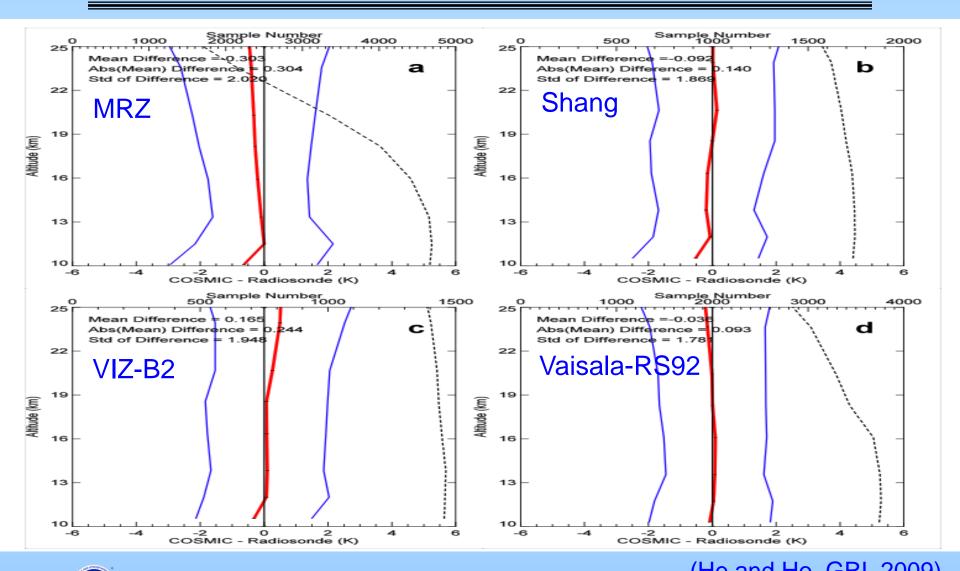
(Ho et al. OPAC special issue, 2009)

TORR

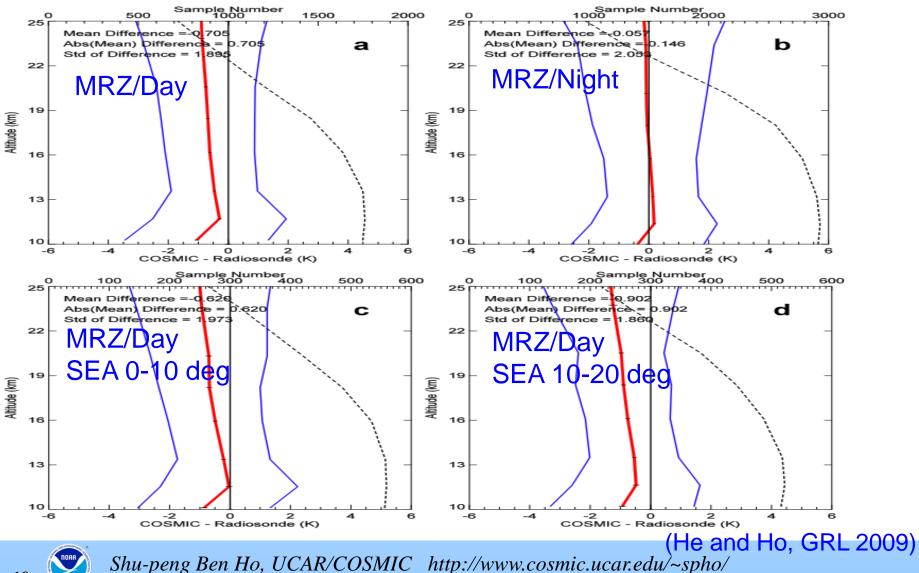
Shu-peng Ben Ho, UCAR/COSMIC http://www.cosmic.ucar.edu/~spho/

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IV. Using RO data to assess the quality of radiosonde data



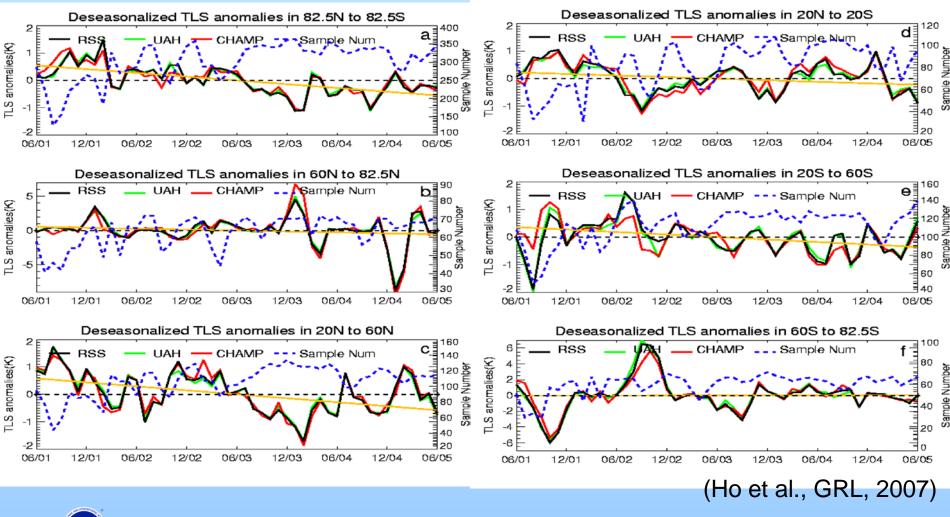
IV. Using RO data to assess the quality of radiosonde data



## Validation Strategy/Results

I. Comparing RO, RSS, UAH temperature time series from 2001 to 2006

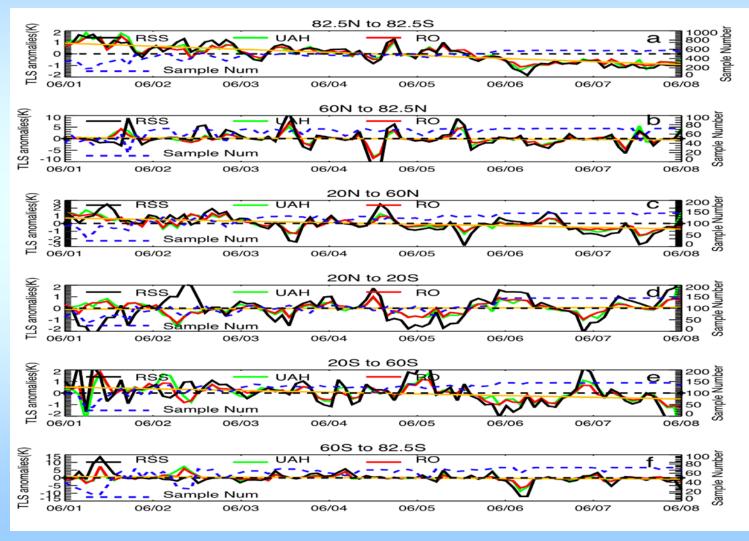
### **De-seasonalized TLS anomalies**



## Validation Strategy/Results

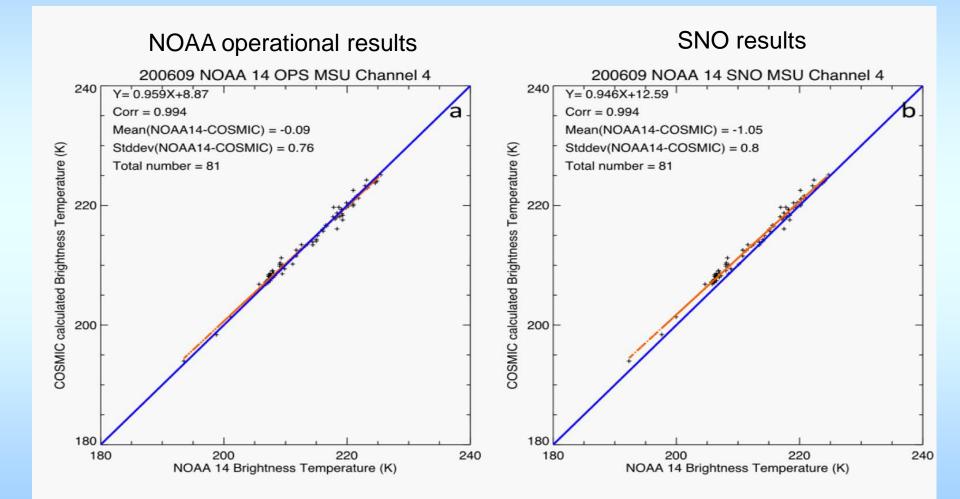
II. Comparing RO, RSS, UAH temperature time series from 2001 to 2008

### **De-seasonalized TLS anomalies**



## Validation Strategy/Results

III. Comparisons of COSMIC/CHAMP data with  $\text{NESDIS}_{\text{NEW}}$  MSU data and  $\text{NESDIS}_{\text{OPR}}$  MSU data



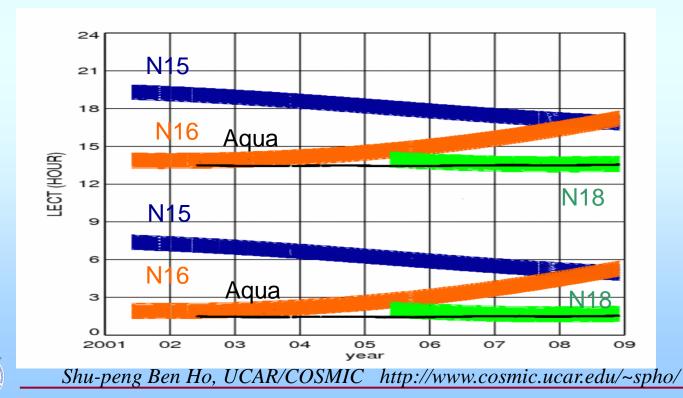
## **Product Maturity**

<Please fill in cells as appropriate; Best guess/estimates acceptable; See Example>

| Maturity | Sensor Use   | Algorith<br>m<br>stability  | Metadata<br>& QA  | Documentation   | Validation   | Public<br>Release  | Science &<br>Applications  |
|----------|--|---|---|---|--|--|--|
| 1        | Research Mission   | Significant<br>changes<br>likely  | Incomplete  | Draft ATBD  | Minimal  | Limited data<br>availability to<br>develop<br>familiarity                                      | Little or none   |
| 2        | Research Mission   | Some<br>changes<br>expected   | Research grade<br>(extensive)   | ATBD Version 1+   | Uncertainty estimated for select locations/times   | Data available<br>but of unknown<br>accuracy; caveats<br>required for use.                     | Limited or<br>ongoing  |
| 3        | Research Missions  | Minimal<br>changes<br>expected  | Research grade<br>(extensive);<br>Meets<br>international<br>standards                                     | Public ATBD; Peer-<br>reviewed algorithm and<br>product descriptions  | Uncertainty estimated<br>over widely distribute<br>times/location by multiple<br>investigators; Differences<br>understood.                               | Data available<br>but of unknown<br>accuracy; caveats<br>required for use.                     | Provisionally used<br>in applications<br>and assessments<br>demonstrating<br>positive value.     |
| 4        | Operational Mission  | Minimal<br>changes<br>expected  | Stable, Allows<br>provenance<br>tracking and<br>reproducibility;<br>Meets<br>international<br>standards   | Public ATBD; Draft<br>Operational Algorithm<br>Description (OAD); Peer-<br>reviewed algorithm and<br>product descriptions                         | Uncertainty estimated<br>over widely distribute<br>times/location by multiple<br>investigators; Differences<br>understood.                               | Data available<br>but of unknown<br>accuracy; caveats<br>required for use.                     | Provisionally used<br>in applications<br>and assessments<br>demonstrating<br>positive value.     |
| 5        | All relevant research<br>and operational<br>missions; unified and<br>coherent record<br>demonstrated across<br>different sensors   | Stable and reproducible   | Stable, Allows<br>provenance<br>tracking and<br>reproducibility;<br>Meeting<br>international<br>standards | Public ATBD, Operational<br>Algorithm Description<br>(OAD) and Validation Plan;<br>Peer-reviewed algorithm,<br>product and validation<br>articles | Consistent uncertainties<br>estimated over most<br>environmental conditions<br>by multiple investigators   | Multi-mission<br>record is publicly<br>available with<br>associated<br>uncertainty<br>estimate | Used in various<br>published<br>applications and<br>assessments by<br>different<br>investigators |
| 6        | All relevant research<br>and operational<br>missions; unified and<br>coherent record over<br>complete series; record<br>is considered<br>scientifically irrefutable<br>following extensive<br>scrutiny | Stable and<br>reproducible;<br>homogeneous<br>and published<br>error budget | Stable, Allows<br>provenance<br>tracking and<br>reproducibility;<br>Meeting<br>international<br>standards | Product, algorithm,<br>validation, processing and<br>metadata described in peer-<br>reviewed literature   | Observation strategy<br>designed to reveal<br>systematic errors through<br>independent cross-checks,<br>open inspection, and<br>continuous interrogation | Multi-mission<br>record is publicly<br>available from<br>Long-Term<br>archive                  | Used in various<br>published<br>applications and<br>assessments by<br>different<br>investigators |

## Issues/Risks & Work- Off Plans

- current or possible future problems:
- SNO issues
- Identify orbital drift effect on MSU/AMSU temperature
- Approaches to get around or mitigate the problem:
- COSMIC/CHAMP has the full diurnal coverage which can be used to identify orbital drift effect on MSU/AMSU.
- Aqua AMSU has no drift.



## **Research- to- Operations or Delivery Plan**

- MSU/AMSU vs. COSMIC/CHAMP monthly calibration coefficients from 2001 to 2009
- Identified radiosodnes sets from 2001 to 2009
- NESDID, RSS, and UAH data
- 1) Applying SNO to calibrated MSU4 BTs
- 2) Applying SNO to calibrated MSU2 and MSU3 BTs
- 3) Applying the calibrated MSU4 BTs to calibrate overlapped 9 years of MSU/AMSU BTs
- 4) Applying the calibrated MSU2 and MSU3 BTs and recalibrating 9 years of MSU/AMSU data
- 5) Documenting the GPS RO metadata and making them available to the public
- 6) Documenting all the comparison and evaluation procedures and temperature records



## Schedule

|  | Aug. 2009-<br>Oct. 2009 | Nov. 2009 –<br>Jan. 2010 | Feb. 2010 –<br>Apr. 2010 | May. 2010<br>– Jul. 2010 |
|--|-------------------------|--------------------------|--------------------------|--------------------------|
| 1) Applying SNO to calibrated MSU4 BTs   | •                       | -                        |                          |                          |
| 2) Applying SNO to<br>calibrated MSU2 and 3<br>BTs   |                         | •                        | •                        |                          |
| <ul> <li>3) Applying the<br/>calibrated MSU4 BTs</li> <li>to calibrate overlapped</li> <li>9 years of MSU/AMSU</li> <li>BTs</li> </ul> | •                       |                          |                          |                          |
| 4) Applying the<br>calibrated MSU2 and<br>MSU3 BTs to SNO and<br>recalibrating 9 years of<br>MSU/AMSU data                             |                         | •                        | •                        |                          |
| 5) Documenting the<br>GPS RO metadata and<br>making them available<br>to the public  |                         | •                        | •                        |                          |
| 6) Documenting all the<br>comparison and<br>evaluation procedures<br>and temperature<br>records  |                         |                          | •                        |                          |
| 7) Delivering all the<br>temperature records to<br>NCDC  |                         |                          | •                        |                          |

## Resources

- Number of personnel employed for project:
  - PI and a visiting scientist
- Key equipment or observatories used:
  - 8CPU PC, Linux system with 4Tbs
  - Satellite RO and microwave sounding data
- Key collaborating projects or personnel
  - NOAA CCDD and SDS Dr. Cheng-Zhi Zou (NOAA/NESDIS)
- NOAA points-of-contact or collaborators
   Bill Murray, NCDC, Cheng-Zhi Zou, NESDIS
- Target NOAA Data Center: NCDC